

Problem 1.

$$\textcircled{a} \quad (e^{i\mathcal{L}t} A)(\theta) = (U_t A)(\theta) = A(\theta + \omega t)$$

take the derivative w/respect to time:

$$(i\mathcal{L} e^{i\mathcal{L}t} A)(\theta) = \omega A'(\theta + \omega t)$$

evaluate at $t=0$:

$$(i\mathcal{L} A)(\theta) = \omega A'(\theta)$$

$$(\mathcal{L} A)(\theta) = -i\omega A'(\theta)$$

$$\textcircled{b} \quad (\mathcal{L} \varphi_n)(\theta) = -i\omega \varphi_n'(\theta) \stackrel{\text{set}}{=} \lambda_n \varphi_n(\theta)$$

$$\varphi_n'(\theta) = i \frac{\lambda_n}{\omega} \varphi_n(\theta)$$

$$\varphi_n(\theta) = c_n e^{i(\lambda_n/\omega)\theta}$$

$$\text{but } \varphi_n(\theta + 2\pi) = \varphi_n(\theta)$$

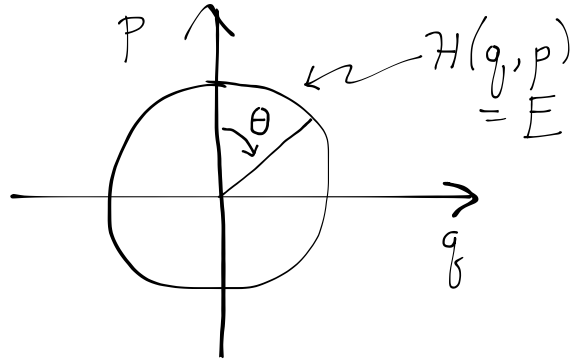
$$\therefore \frac{\lambda_n}{\omega} = n, \text{ where } n \text{ is an integer}$$

$$\text{Normalization: } 1 = \int_0^{2\pi} |\varphi_n(\theta)|^2 d\theta$$

$$\rightarrow c_n = \frac{1}{\sqrt{2\pi}}$$

$$\boxed{\varphi_n(\theta) = \frac{1}{\sqrt{2\pi}} e^{in\theta}, \quad \lambda_n = n\omega}$$

$$\begin{aligned} \textcircled{c} \quad p(\theta) &= \sqrt{2mE} \cos \theta \\ q(\theta) &= \sqrt{\frac{2E}{m\omega^2}} \sin \theta \\ \dot{\theta} &= \omega \end{aligned}$$



(Easy to verify: $\dot{q} = \frac{p}{m}$, $\dot{p} = -m\omega^2 q$)

$$p(\theta) = \sqrt{2mE} \cos \theta = \sqrt{\pi m E} \varphi_{+1}(\theta) + \sqrt{\pi m E} \varphi_{-1}(\theta)$$

$$\text{i.e. } \alpha_n = \begin{cases} \sqrt{\pi m E} & \text{if } n = \pm 1 \\ 0 & \text{otherwise} \end{cases}$$

$$(U_t p)(\theta) = e^{i\mathcal{L}t} \alpha (\varphi_{+1} + \varphi_{-1}) \quad \alpha \equiv \sqrt{2mE}$$

$$= \alpha (e^{i\omega t} \varphi_{+1} + e^{-i\omega t} \varphi_{-1})$$

$$= \sqrt{2mE} \cos(\theta + \omega t) = p(\theta + \omega t) \quad \checkmark$$

$$\textcircled{d} \quad f_0(\theta) = \sum_n \beta_n \varphi_n(\theta)$$

$$\beta_n = \langle n | f_0 \rangle = \frac{1}{\sqrt{2\pi}} \int_0^{2\pi} d\theta' e^{-in\theta'} f_0(\theta')$$

$$\therefore e^{-i\mathcal{L}t} f_0(\theta) = \sum_n \left[\frac{1}{\sqrt{2\pi}} \int_0^{2\pi} d\theta' e^{-in\theta'} f_0(\theta') \right] e^{-in\omega t} \varphi_n(\theta)$$

$$= \sum_n \frac{1}{2\pi} \int_0^{2\pi} d\theta' e^{-in(\theta' + \omega t - \theta)} f_0(\theta')$$

$$\begin{aligned}
&= \int_0^{2\pi} d\theta' \left[\frac{1}{2\pi} \sum_n e^{-in(\theta' + \omega t - \theta)} \right] f_0(\theta) \\
&= \int_0^{2\pi} d\theta' \delta(\theta' + \omega t - \theta) f_0(\theta) \\
&= f_0(\theta - \omega t) = f(\theta, t) \quad \checkmark
\end{aligned}$$

Here we've used the following series representation of the Dirac delta function:

$$\delta(x) = \frac{1}{2\pi} \sum_{n=-\infty}^{+\infty} e^{inx}$$

Problem 2.

$$\textcircled{a} \quad f(x, t + \delta t) = \int dx_0 \, f(x_0, t) \mathcal{N} \exp \left[-\frac{(x - x_0 + \alpha x_0 \delta t)^2}{4D \delta t} \right]$$

$$\epsilon \equiv x - x_0 \quad = \int d\epsilon \, f(x - \epsilon, t) \mathcal{N} \exp \left[-\frac{(\epsilon + \alpha(x - \epsilon) \delta t)^2}{4D \delta t} \right]$$

$$\epsilon + \alpha(x - \epsilon) \delta t = (1 - \alpha \delta t) \epsilon + \alpha x \delta t$$

$$\therefore \frac{(\epsilon + \alpha(x - \epsilon) \delta t)^2}{4D \delta t} = \frac{(1 - \alpha \delta t)^2}{4D \delta t} \left(\epsilon + \frac{\alpha x \delta t}{1 - \alpha \delta t} \right)^2$$

$$f(x, t + \delta t) = \int d\epsilon \, f(x - \epsilon, t) \frac{1}{\sqrt{4\pi D \delta t}} \exp \left[-\frac{(1 - \alpha \delta t)^2}{4D \delta t} \left(\epsilon + \frac{\alpha x \delta t}{1 - \alpha \delta t} \right)^2 \right]$$

$$= \frac{1}{1 - \alpha \delta t} \int d\epsilon \, f(x - \epsilon, t) \frac{1}{\sqrt{2\pi \sigma^2}} \exp \left[-\frac{(\epsilon + \beta x \delta t)^2}{2\sigma^2} \right]$$

$$\sigma^2 = \frac{2D \delta t}{(1 - \alpha \delta t)^2}, \quad \beta = \frac{\alpha}{1 - \alpha \delta t}$$

$$\textcircled{b} \quad f(x, t + \delta t) = \frac{1}{1 - \alpha \delta t} \int d\epsilon \, f(x - \epsilon, t) g(\epsilon)$$

where $g(\epsilon)$ is a Gaussian with mean $-\beta x \delta t$
& variance σ^2

Expand $f(x - \epsilon, t)$ to $\mathcal{O}(\epsilon^2)$ we get the
desired result (Eq. 13), with

$$I_0 = \int d\epsilon \, g(\epsilon) = 1$$

$$I_1 = \int d\epsilon \, -\epsilon g(\epsilon) = \beta x \delta t$$

$$\begin{aligned}
 I_2 &= \int d\epsilon \frac{\epsilon^2}{2} g(\epsilon) = \frac{\sigma^2}{2} + \frac{(\beta x \delta t)^2}{2} \\
 &= \frac{D \delta t}{(1 - \alpha \delta t)^2} + \frac{(\beta x \delta t)^2}{2}
 \end{aligned}$$

© To $O(\delta t)$ we get*

$$f(x, t + \delta t) = f(x, t) + \delta t \left[\alpha f(x, t) + \alpha x f'(x, t) + D f''(x, t) \right]$$

$$\text{i.e. } \frac{\partial f}{\partial t} = \alpha f + \alpha x f' + D f'' = \alpha \frac{\partial}{\partial x} (x f) + D \frac{\partial^2 f}{\partial x^2}$$

$$* \text{ using } \frac{1}{1 - \alpha \delta t} = 1 + \alpha \delta t + O(\delta t^2)$$

$$\& \quad \beta \delta t = \alpha \delta t + O(\delta t^2)$$

Problem 3

② Net displacement over K steps:

$$\Delta = \sum_{i=1}^K \delta_i = d \sum_{i=1}^K x_i, \quad x_i = \pm 1$$

$$\langle \Delta \rangle = d \sum_i x_i = d \cdot K \cdot (p - q)$$

$$\begin{aligned} \langle \Delta^2 \rangle &= d^2 \sum_{i,j} \langle x_i x_j \rangle = \langle x_i \rangle \langle x_j \rangle \\ &= d^2 \sum_{i=1}^K \langle x_i^2 \rangle + d^2 \sum_{i=1}^K \sum_{\substack{j=1 \\ j \neq i}}^K \langle x_i x_j \rangle \end{aligned}$$

$$= Kd^2 + K(K-1)d^2(p-q)^2$$

$$\langle \Delta^2 \rangle - \langle \Delta \rangle^2 = 4pq d^2 K$$

$$2D = \lim_{K \rightarrow \infty} \frac{\langle \Delta^2 \rangle - \langle \Delta \rangle^2}{K \epsilon} = \frac{4pq d^2}{\epsilon}$$

D = diff'n coefficient

$$v = \text{drift coefficient} = \frac{\langle \Delta \rangle}{K \epsilon} = \frac{d}{\epsilon} (p - q)$$

$$\boxed{\frac{\partial f}{\partial t} = - \frac{d}{\epsilon} (p - q) \frac{\partial f}{\partial x} + 2pq \frac{d^2}{\epsilon} \frac{\partial^2 f}{\partial x^2}}$$

$$\rightarrow \frac{d^2}{2\epsilon} \frac{\partial^2 f}{\partial x^2} \quad \text{when } p = q = \frac{1}{2}$$

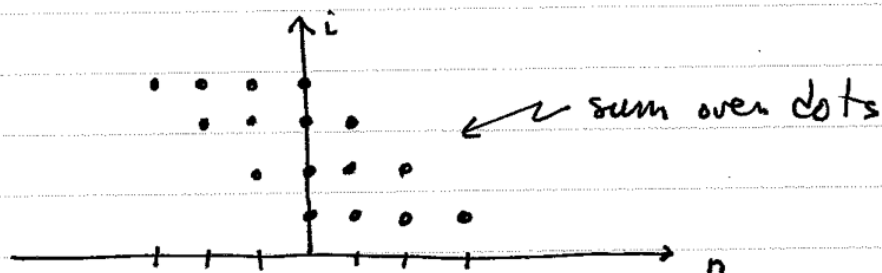
$$b) \Delta = d \sum_i x_i \quad \text{as before}$$

$$\Delta^2 = d^2 \sum_{ij} x_i x_j$$

$$\langle \Delta^2 \rangle = d^2 \sum_{ij} \langle x_i x_j \rangle$$

$$= d^2 \sum_{ij} c_{j-i} \quad c_n \equiv \langle x_0 x_n \rangle$$

$$= d^2 \sum_{i=1}^K \sum_{n=1-i}^{K-i} c_n$$



$$\langle \Delta^2 \rangle = d^2 \sum_{n=-K+1}^{K-1} (K - |n|) c_n$$

$$= K d^2 \sum_{n=-K+1}^{K-1} \left(1 - \frac{|n|}{K}\right) c_n$$

$$\frac{\langle \Delta^2 \rangle}{K} \xrightarrow{K \rightarrow \infty} d^2 \sum_{n=-\infty}^{\infty} c_n \stackrel{\text{set}}{=} 2 D \epsilon$$

$$D = \frac{d^2}{2\epsilon} \sum_{n=-\infty}^{\infty} c_n$$

$$c_0 = \langle x_0^2 \rangle = 1 \quad c_{-n} = c_n \quad c_n = \langle x_0 x_n \rangle$$

For a given sequence $x_0 x_1 \dots x_n$,

$$x_0 x_n = (-1)^l \text{ where}$$

~~total~~ $l = \#$ of "reversals" in the sequence

E.g. for $n=4$: $(+ + + + +) \leftarrow$ no reversals
 $(x_0 \ x_1 \quad \quad \quad x_4) \quad (l=0)$

$(+ - + + -) \leftarrow$ 3 reversals
 etc.

l can range from 0 to n ,
 & the probability to observe l reversals is:

$$\binom{n}{l} p^{n-l} q^l$$

$$\therefore \langle x_0 x_n \rangle = \sum_{l=0}^n \binom{n}{l} p^{n-l} q^l (-1)^l = (p-q)^n$$

$$= \delta^n \quad (n \geq 0)$$

$$\sum_{n=-\infty}^{+\infty} c_n = \left(\sum_{n=-\infty}^{-1} c_n \right) + c_0 + \left(\sum_{n=1}^{\infty} c_n \right)$$

$$= c_0 + 2 \sum_{n=1}^{\infty} c_n$$

$$= -c_0 + 2 \sum_{n=0}^{\infty} c_n$$

$$= -1 + 2 \sum_{n=0}^{\infty} (1 + \delta + \delta^2 + \dots)$$

$$= -1 + \frac{2}{1-\delta} = \frac{1+\delta}{1-\delta} = \frac{p}{q}$$

$$D = \frac{d^2}{2\epsilon} \frac{p}{q}$$

drift term $v=0$ by symmetry

$$\boxed{\frac{\partial f}{\partial t} = \frac{d^2}{2\epsilon} \frac{p}{q} \frac{\partial^2 f}{\partial x^2}}$$

$$\rightarrow \frac{d^2}{2\epsilon} \frac{\partial^2 f}{\partial x^2} \text{ when } p=q=\frac{1}{2}$$

Problem 4

(a) $f(p, t)$ = momentum distribution

$$h(\lambda, t) = \int dp f(p, t) e^{\lambda p} = \langle e^{\lambda p} \rangle$$

$$g(\lambda, t) = \ln h(\lambda, t) \quad \leftarrow \text{generating function}$$

$$\frac{\partial h}{\partial t} = \int dp \frac{\partial f}{\partial t} e^{\lambda p} = \int dp e^{\lambda p} \frac{\partial}{\partial p} \left[\frac{\partial_p}{m} f - F(t) f + D_p \frac{\partial f}{\partial p} \right]$$

$\nearrow q E_0 \cos \omega t$

Integrating by parts gives:

$$\frac{\partial h}{\partial t} = -\lambda \int dp e^{\lambda p} \left[\frac{\partial_p}{m} f - F(t) f + D_p \frac{\partial f}{\partial p} \right]$$

$$= -\lambda \frac{\partial}{m} \frac{\partial h}{\partial \lambda} + \lambda F(t) h + \lambda^2 D_p h$$

$$\frac{\partial g}{\partial t} = \frac{1}{h} \frac{\partial h}{\partial t} = -\lambda \frac{\partial}{m} \frac{\partial g}{\partial \lambda} + \lambda F(t) + \lambda^2 D_p$$

$$\text{But } g(\lambda, t) = \sum_{l=1}^{\infty} \frac{\kappa_l}{l!} \lambda^l \quad \therefore \frac{\partial g}{\partial t} = \sum_{l=1}^{\infty} \frac{1}{l!} \dot{\kappa}_l \lambda^l$$

$$\frac{\partial g}{\partial \lambda} = \sum_{l=1}^{\infty} \frac{1}{(l-1)!} \kappa_l \lambda^{l-1}$$

$$\text{So: } \dot{\kappa}_1 \lambda + \frac{1}{2} \dot{\kappa}_2 \lambda^2 + \frac{1}{6} \dot{\kappa}_3 \lambda^3 + \dots$$

$$= -\frac{\partial}{m} \left(\kappa_1 \lambda + \kappa_2 \lambda^2 + \frac{1}{2} \kappa_3 \lambda^3 + \dots \right) + \lambda F(t) + \lambda^2 D_p$$

Collecting terms by power of λ , we get:

$$\begin{aligned}\dot{K}_1 &= -\frac{\gamma}{m} K_1 + F(t) \\ \frac{1}{2} \dot{K}_2 &= -\frac{\gamma}{m} K_2 + D_f \\ \frac{1}{n} \dot{K}_n &= -\frac{\gamma}{m} K_n, \quad n \geq 3\end{aligned}$$

$$(b) \quad n \geq 3: K_n(t) = K_n(0) e^{-n\gamma t} \xrightarrow{t \rightarrow \infty} 0 \quad \nu \equiv \frac{\gamma}{m}$$

$$\langle p \rangle = K_1 = \mu \quad (\text{mean of the distribution})$$

$$\dot{\mu} = -\nu\mu + \alpha \cos \omega t, \quad \alpha \equiv g E_0$$

$$\mu(t) = \mu(0) e^{-\nu t} + \int_0^t ds \alpha \cos(\omega s) e^{-\nu(t-s)}$$

$$= \mu(0) e^{-\nu t} + \alpha \operatorname{Re} \frac{e^{i\omega t} - e^{-\nu t}}{\nu + i\omega}$$

$$\xrightarrow{t \rightarrow \infty} \frac{g E_0 m}{\sqrt{\gamma^2 + m^2 \omega^2}} \cos(\omega t - \varphi), \quad \varphi = \tan^{-1} \frac{m\omega}{\gamma}$$

$$\sigma^2 = K_2(t) = \left[K_2(0) - \frac{m D_f}{\gamma} \right] e^{-2\nu t} + \frac{m D_f}{\gamma} \xrightarrow{t \rightarrow \infty} m \beta^{-1}$$

$$(c) \quad F = g E_0 \cos \omega t, \quad \nu = \frac{\gamma}{m}$$

$$\langle \text{power} \rangle = \frac{g E_0}{m} \langle p \rangle \cos \omega t = \frac{g^2 E_0^2}{\sqrt{\gamma^2 + m^2 \omega^2}} \cos(\omega t - \varphi) \cos \omega t$$

Averaging over one period $\left(\frac{2\pi}{\omega}\right)$ gives:

$$\overline{\langle \text{power} \rangle} = \frac{g^2 E_0^2}{\sqrt{\gamma^2 + m^2 \omega^2}} \frac{1}{2} \cos \varphi = \frac{1}{2} \frac{\gamma g^2 E_0^2}{\gamma^2 + m^2 \omega^2} \quad \leftarrow$$

time-averaged dissipation

$$\textcircled{d} \quad \omega \ll \frac{\gamma}{m} : \quad \varphi \rightarrow 0, \quad \gamma^2 + m^2 \omega^2 \rightarrow \gamma^2$$

$$\langle p \rangle = \frac{q E_0 m}{\gamma} \cos \omega t$$

$$\overline{\langle \text{power} \rangle} = \frac{q^2 E_0^2}{2\gamma}$$

We get the same results by realizing that for low frequencies the average force due to friction, $-\frac{\gamma}{m} \langle p \rangle$, is balanced by the external force $q E_0 \cos \omega t$, i.e. the particle is always at "terminal velocity" (apart from fluctuations).